Stationary states of the one-dimensional discrete-time facilitated symmetric exclusion process

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ABSTRACT
We describe the extremal translation invariant stationary (ETIS) states of the facilitated exclusion process on \( \mathbb{Z} \). In this model, all particles on sites with one occupied and one empty neighbor jump at each integer time to the empty neighbor site, and if two particles attempt to jump into the same empty site, we choose one randomly to succeed. The ETIS states are qualitatively different for densities \( \rho < 1/2 \), \( \rho = 1/2 \), and \( 1/2 < \rho < 1 \), but in each density region, we find states that may be grouped into families, each of which is in natural correspondence with the set of all ergodic measures on \( \{0, 1\}^\mathbb{Z} \). For \( \rho < 1/2 \), there is one such family, containing all the ergodic states in which the probability of two adjacent occupied sites is zero. For \( \rho = 1/2 \), there are two families, in which configurations translate to the left and right, respectively, with constant speed 2. For the high density case, there is a continuum of families. We show that all ETIS states at densities \( \rho \leq 1/2 \) belong to these families and conjecture that also at high density there are no other ETIS states. We also study the possible ETIS states that might occur if the conjecture fails.

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I. INTRODUCTION

A facilitated exclusion process, sometimes called a conserved lattice gas, is a model of particles moving on a lattice, usually \( \mathbb{Z}^d \) or a finite portion of it with periodic boundary conditions, in which a particle can jump to a neighboring (empty) site only if another of its neighboring sites is occupied (by a facilitating particle). Many variations of such models have been studied in both the physics and mathematics literature, with (i) different values of the dimension \( d \); (ii) implementations of the dynamics in either continuous time, in which each facilitated particle attempts to jump independently at a certain rate (or equivalently, in a finite system, with random sequential updating), or discrete time, in which all facilitated particles attempt to jump simultaneously, at integer times; and (iii) for \( d = 1 \), various distributions, symmetric, partially asymmetric, or totally asymmetric, governing the choice of target site (for \( d \geq 2 \), we are aware of studies only of the symmetric distribution). For the one-dimensional case in continuous time, see Refs. 1–4 for symmetric dynamics, Refs. 5–9 for totally asymmetric dynamics, and Ref. 10 for the general (symmetric and partially or totally asymmetric) case. For the one-dimensional case in discrete time, with totally asymmetric dynamics, see Refs. 11 and 12. For the higher dimensional case in discrete time, see Refs. 13 and 14. Reference 4 studies, in continuous time with symmetric dynamics, the intermediate case in which the lattice is a ladder with two infinite rows.

In this paper, we consider the case of symmetric discrete-time dynamics on the one-dimensional lattice \( \mathbb{Z} \); so far as we know, we are the first to do so. (In Remark 1.1, we review briefly, for comparison, the situation for one-dimensional continuous time dynamics\textsuperscript{10,11}). We
find a variety of interesting phenomena that do not occur in the continuous-time $d = 1$ model and have not been reported in studies of the higher-dimensional discrete-time version.

The configuration space of our model is $X = \{0,1\}^Z$; if $\eta$ is a configuration in $X$, then we say that a site $i$ with $\eta(i) = 1$ is occupied by a particle, and a site with $\eta(i) = 0$ is unoccupied or empty. The (stochastic) dynamics is defined as follows: if $\eta_t$ is the configuration at time $t$, $t \in \mathbb{Z}$, then each particle in $\eta_t$ with exactly one occupied neighboring site attempts to jump to its unoccupied neighboring site; the jump takes place unless two particles attempt to jump on the same site, in which case one of them is chosen at random to succeed, with each choice equally likely. $\eta_{t+1}$ is the resulting configuration.

Our goal is to classify the states—probability measures on $X$—which are translation invariant (TI) and stationary for the Facilitated Simple Symmetric Exclusion Process (F-SSEP) dynamics, the TIS states. Every TIS state is a convex combination of the extremal TI (ETI) states, that is, of the TIS states that are not proper convex combinations of others, so it suffices to find the ETIS states. The ETIS states need not be extremal TI (ETI) — i.e., ergodic under translations — but since the particles are neither created nor destroyed, extremality in the class of TIS states suffices to guarantee (see Lemma 2.4) that each ETIS state will be supported on the set $X_\rho$ of configurations having particle density $\rho$ for some $\rho$ with $0 \leq \rho \leq 1$, that is, satisfying

$$\lim_{N \to \infty} \frac{1}{N} \sum_{i=1}^N \eta_i = \lim_{N \to \infty} \frac{1}{N} \sum_{i=-N}^{-1} \eta_i = \rho.$$ (1.1)

We will say that a TI state has density $\rho$ if it is supported on $X_\rho$. [Note that this condition implies that for each $i \in \mathbb{Z}$, the expected value of $\eta(i)$ is $\rho$ but is, in fact, a stronger statement.]

It is convenient to consider also a second particle system on $\mathbb{Z}$, again evolving in discrete time: the symmetric stack model (SSM). (To our knowledge, this model has not been considered elsewhere.) In this model, there are no restrictions on the number of particles at any site so that the configuration space is $X = \mathbb{Z}_+^N$, where $\mathbb{Z}_+ = \{0, 1, 2, \ldots\}$. We denote stack configurations by boldface letters, and to distinguish explicit stack configurations from F-SSEP particle configurations, we will use italics for the former so that for $n \in \mathbb{N}$, we might have $\mathbf{n}(0) = 2$. To specify the evolution of the SSM, let us say that the stack at site $i$ is short if $\eta(i) \leq 1$ and tall otherwise. Then, in the transition from $\mathbf{n}_t$ to $\mathbf{n}_{t+1}$, either zero or one particle moves along each bond $(k, k+1)$, either to the left or to the right: if the stacks at $k$ and $k+1$ are both short, then no particle moves on the bond; if one is short and one tall, then a particle moves from the tall to the short stack; and if both are tall, then a particle moves from one to the other in a randomly chosen direction, with each direction equally likely.

For the SSM, we again speak of TIS and ETIS states and, for $\rho < \infty$, of states of density $\rho$, where the latter are those supported on $\hat{X}_\rho$, the set of SSM configurations of density $\rho$, defined in parallel with (1.1). If the expected value of $\mathbf{n}(0)$ is finite in a TI state on $X$, then we say that the state is regular. A TI state on $X$ is called regular if it gives zero probability to the configuration $\eta$ for which $\eta(i) = 1$ for all $i$.

The SSM is connected with the F-SSEP through a substitution map $\phi : \hat{X} \to X$: if $\eta \in \hat{X}$, then $\phi(\eta)$ is obtained by replacing each $\mathbf{n}(i)$ with a zero particle by $\mathbf{n}(i)$ ones. Such a mapping has also been used to relate exclusion and zero range processes; see, e.g., Refs. 15 and 16.) In Appendix A, we show that this substitution, and members of a large class of similar substitutions, gives rise to a bijection of the regular TI or ETI states of the models related by the substitution. Moreover, we show there that for the particular substitution $\phi$ above, the bijection $\Phi_\rho$ of the regular TI states is also a bijection from the regular TIS or ETIS states of the SSM to those of the F-SSEP. Thus, for the question of interest here—the nature and classification of the TIS states—the F-SSEP and SSM are essentially equivalent, and we can and will pass freely from one to the other. Note that if $\mathbf{n}$ has density $\rho$, then $\phi(\mathbf{n})$ has density $\rho = \hat{\rho}/(1 + \hat{\rho})$; correspondingly, $\Phi_\rho$ carries regular SSM states of density $\rho$ to regular F-SSEP states of density $\rho$.

Recall now that each regular ETIS state is associated with some density $\rho$ in the F-SSEP or equivalently $\hat{\rho} = \rho/(1 - \rho)$ in the SSM. The classification of the ETIS states of the models is qualitatively different in the three density regions $0 \leq \rho < 1/2$, $1/2 < \rho < 1$, and $1 < \rho < \infty$. The states in the first two of these regions are, of course, all regular.

Consider first the low density region. The set of ETIS states of the SSM with $0 \leq \rho < 1/2$, $\rho = 1/2$, and $1/2 < \rho < 1$ or, equivalently, $0 \leq \hat{\rho} < 1$, $\hat{\rho} = 1$, and $1 < \hat{\rho} < \infty$. The states in the first two of these regions are, of course, all regular.

The set of ETIS states of the SSM with $0 \leq \hat{\rho} < 1$ is precisely the set of ETI states supported on $\mathbb{F} = \hat{X}$, the set of frozen SSM configurations for which every stack has height zero or one (note that, in fact, $\mathbb{F} = \hat{X}$). For the F-SSEP, the corresponding result is that the ETIS states are the ETI states supported on the set $\mathbb{F}$ of frozen F-SSEP configurations: those in which no two adjacent sites are occupied and, hence, no particle jumps are possible.

When $\hat{\rho} = 1$ in the SSM ($\rho = 1/2$ in the F-SSEP), there are two families of ETIS states in each model; these describe patterns moving to the left or to the right, respectively, with speed 1 in the SSM and speed 2 in the F-SSEP. In the SSM, the left-moving family consists of all ETI states supported on $\hat{X}_{\text{left}}$, the set of configurations in which no stack has height more than 2, a stack of height 2 can be followed only by one of height 0, and a stack of height 0 can be preceded only by one of height 2. Similarly, the right-moving family consists of the ETI states on $\hat{X}_{\text{right}}$, the spatial reflection of $\hat{X}_{\text{left}}$. Two states belong to both families: the state $\hat{\rho}^{(1)}$ (which is also one of the low-density states of the previous paragraph) supported on the single configuration in which all stacks have height 1 and the state $\hat{\rho}^{(2)}$ supported with equal probability on the two configurations in which stacks of height 0 and 2 alternate. The left- and right-moving families in the F-SSEP are obtained from those of the SSM via the map $\Phi_{\hat{\rho}}$. All TIS states in the high density region of the SSM, $1 < \hat{\rho}$, are supported on $\hat{X}^* = \hat{X}$, the set of configurations for which no two adjacent sites both have short stacks. On $\hat{X}^*$, the dynamics preserves the parity of each stack height so that if for $\sigma \in X$, we let $X^*_\sigma \in \hat{X}^*$ be the set of configurations $\mathbf{n}$ for which $\mathbf{n}(i)$ has parity $(-1)^{\sigma(i)}$, then each $X^*_\sigma$ is invariant for the dynamics. (In these circumstances, we call $\sigma$ a parity sequence.)
Let $e$ be the parity sequence with $e(i) = 0$ for all $i$ so that $X_e^*$ is the set of configurations for which each stack height is even and there are no adjacent zeros. For each $\hat{\rho}_e \geq 1$, we find an ETIS state $\mu^{(\hat{\rho})}_e$ on $X_e^*$ of density $\hat{\rho}_e$, which we conjecture to be unique: if $\hat{\rho}_e = 1$, then $\mu^{(\hat{\rho})}_e$ is the state $\rho^{(\hat{\rho})}_e$ described above, while if $\hat{\rho}_e > 1$, then $\mu^{(\hat{\rho})}_e$ is a Gibbs state for an interaction that is simply a one-body potential together with the constraints—hard-core and evenness—implicit in $X_e^*$. Further, for each such $\hat{\rho}_e$, we obtain from $\mu^{(\hat{\rho})}_e$ a family of regular ETIS states on $X^*$ and show that if the conjecture mentioned above holds, then these are all such states. Specifically, for each $\hat{\rho}_e \geq 1$ and each ETI state $\lambda$ on $X$, there is an ETIS state $\mu^{(\hat{\rho}),\lambda}_e$ for the SSM; $\mu^{(\hat{\rho}),\lambda}_e$ has the distribution of $\eta + \sigma$ (pointwise addition), where $\eta$ has distribution $\mu^{(\hat{\rho})}_e$, $\sigma$ has distribution $\lambda$, and $\eta$ and $\sigma$ are independent. Note that if $\lambda$ has density $\kappa$, then $\mu^{(\hat{\rho}),\lambda}_e$ has density $\hat{\rho}_e + \kappa$. The corresponding families for the F-SSEP are obtained via the map $\Phi_e$.

Remark 1.1. A discussion of the TIS states of the continuous-time version of the model, generalized to include an asymmetry in the jumps, was given in Ref. 10. The asymmetry is controlled by a parameter $p \in [0, 1]$: a particle at site $i \in \mathbb{Z}$ jumps to site $i + 1$ (respectively, $i - 1$) with rate $p$ (respectively, $1 - p$), provided that site $i - 1$ (respectively, $i + 1$) is occupied and site $i + 1$ (respectively, $i - 1$) is empty. For $p \leq 1/2$, the TIS states are, as for the current model, just the TI states supported on $F$; but for the continuous-time model, it was possible to determine the limiting state $\mu$ when the initial state $\mu_0$ is Bernoulli; rather surprisingly, $\mu$ is independent of $p$. ($\mu$ is also the limiting state, with initial state $\mu_0$, under totally asymmetric discrete-time dynamics.) For $p > 1/2$, the unique TIS state is supported with equal probability on the two configurations in which occupied and empty sites alternate. For each $p > 1/2$, there is again a unique TIS state, the Gibbs state for a particle system in which the only interaction is an exclusion rule forbidding adjacent empty sites; the uniqueness was established via a coupling of the model with the usual asymmetric simple exclusion process.

II. PRELIMINARY CONSIDERATIONS

We here introduce some further notation and provide some simple results for the F-SSEP and SSM models, often speaking in terms of the F-SSEP with the understanding that parallel notation will be used, and similar results hold, for the SSM. Let us mention several pieces of general notation: for any sets $A$ and $B$, function $f : A \to B$, and measure $\lambda$ on $A$, we let $f_* \lambda$ be the measure on $B$ with $(f_* \lambda)(C) = \lambda(f^{-1}(C))$; moreover, if $B = \mathbb{B}$, we let $\lambda(f) = \int f \ d\lambda$ denote the expected value of $f$ under $\lambda$. When $C \subseteq B$, we let $1_C : B \to \{0, 1\}$ denote the indicator function of the set $C$. If $S$ is a finite set, then $|S|$ denotes the size of $S$.

Recall from Sec. I that the configuration spaces for these models are $X := \{0, 1\}^\mathbb{Z}$ and $\tilde{X} := \mathbb{Z}_e^\mathbb{Z}$, respectively, with $\eta \in \tilde{X}$ and $\mathbf{n} \in \tilde{X}$ denoting configurations. For $\eta \in X$ and $j, k \in \mathbb{Z}$ with $j \leq k$, we let $\eta(j : k) = (\eta(i))_{i \in [j,k]}$ denote the portion of the configuration $\eta$ lying between sites $j$ and $k$ (inclusive). We will occasionally use string notation for configurations or partial configurations, writing, for example, $\eta(0 : 4) = \eta(0) \cdots \eta(4) = 010110 = 010101$. $\tau : X \to \{\text{or } \tilde{X} \to \tilde{X}\}$ denotes the translation operator: if $\eta \in X$, then $(\tau_\eta)(i) = \eta(i + 1)$; if $f$ is any function on $X$, then $\tau f(\eta) = f(\tau^{-1} \eta)$; and if $\mu$ is a (Borel) measure on $X$, then $\tau$ acts on $\mu$ via $\tau_* \mu$.

It will sometimes be convenient to associate to each F-SSEP configuration $\eta \in X$ a height profile $h_\eta : \mathbb{Z} \to \mathbb{Z}$, which, in the usual convention, rises by one unit when $\eta(i) = 0$ and sinks by one unit when $\eta(i) = 1$. Specifically,$$h_\eta(k) = \begin{cases} 0 & \text{if } k = 0, \\ \sum_{i=1}^k (-1)^{\eta(i)} & \text{if } k > 0, \\ -\sum_{i=k+1}^0 (-1)^{\eta(i)} & \text{if } k < 0. \end{cases} \quad (2.1)$$

We do not introduce height profiles for SSM configurations.

From the somewhat informal description of the dynamics of the models given in Sec. I, it is straightforward but tedious to specify, for a configuration $\eta \in X$ and a measurable subset $A \subseteq X$, the transition kernel $Q(\eta, A)$ of the F-SSEP Markov process, or similarly the kernel $\hat{Q}(\mathbf{n}, B)$ for the SSM model. We omit the details. A measure $\mu$ on $X$ is stationary if $\mu = \mu Q$; here, $(\mu Q)(A) = \int X Q(\eta, A) d\mu$ [we also write $\mu Q^n := (\mu Q^{n-1})Q$ for $n \geq 2$].

In the remainder of this paper, we will consider primarily regular (see Sec. I) states on $X$ and $\tilde{X}$; the sets of regular TI, ETI, TIS, and ETIS states for the SSM are denoted by $\mathcal{M}(X), \overline{\mathcal{M}}(X), \mathcal{M}(\tilde{X})$, and $\overline{\mathcal{M}}(\tilde{X})$, respectively. We write similarly $\overline{\mathcal{M}}(\tilde{X})$, etc., as well as $\mathcal{M}(A)$, $\mathcal{M}(\tilde{A})$, etc., for $A \subseteq X$ or $\tilde{A} \subseteq \tilde{X}$ TI sets. As a consequence of the results of Appendix A (see also the discussion of Sec. I), we have immediately the following theorem:

**Theorem 2.1.** There exists a bijection, $\Phi_e : \mathcal{M}(\tilde{X}) \to \mathcal{M}(X)$, arising from the substitution map $\phi$ defined in Sec. I, which satisfies $\Phi_e(\overline{\mathcal{M}}(\tilde{X})) = \overline{\mathcal{M}}(X)$, $\Phi_e(\mathcal{M}(\tilde{X})) = \mathcal{M}(X)$, and $\Phi_e(\overline{\mathcal{M}}(\tilde{X})) = \overline{\mathcal{M}}(X)$. $\Phi_e$ carries states of density $\rho$ to states of density $\hat{\rho}/(1 + \hat{\rho})$. Moreover, if $\tilde{A} \subseteq \tilde{X}$ is TI, then there is a similarly defined bijection from $\overline{\mathcal{M}}(\tilde{A})$ to $\mathcal{M}(A)$, etc., where $A$ is the minimal TI subset of $X$ containing $\tilde{A}$.

Remark 2.2. It is clear that one may also define, in a straightforward way, models with a fixed number of particles moving on a finite ring under either the F-SSEP or SSM dynamics. These models will play a role in Secs. IV and V. B.
Since we are studying stationary states, it is natural to introduce the set of space–time F-SSEP configurations \( X_2 = \{0, 1\}^{Z^2} \) of \( \{\mu(t)_{(x,y)}\} \); a state \( \mu \in \mathcal{M}(X) \) that is stationary for the dynamics induces a “path measure” on \( X_2 \), invariant under vertical translation, which we denote \( P_\mu, \hat{X}_2 \) and \( \hat{P}_2 \) denote the corresponding SSM quantities.

In Secs. III–V, we will describe all ETIS states for the two models. As indicated in Sec. 1, these fall into certain natural groups, which we will call \( \lambda \)-families. In this context, we write \( \mathcal{L} \) for the set of ergodic TI measures on \( X \) [in fact, \( \mathcal{L} = \mathcal{M}(X) \)], but the special role that this space plays here motivates a special symbol.

Definition 2.3. A \( \lambda \)-family is a collection of ETIS states for either the SSM or the F-SSEP, which is bijectively equivalent (with a “natural” bijection) to \( \mathcal{L} \). We think of \( \mathcal{L} \) as indexing the \( \lambda \)-family, and let \( \lambda \in \mathcal{L} \) denote a typical index. We will typically write \( \hat{F}_\lambda \) and \( \hat{F}_\lambda \) for \( \lambda \)-families for the SSM and F-SSEP, respectively, with \( \cdot \) as a subscript distinguishing the various families and with \( \mathcal{F}_\lambda = \Phi_\lambda(\hat{F}_\lambda), \mathcal{P}_\lambda : \mathcal{L} \rightarrow \mathcal{F}_\lambda \) and \( \mathcal{S}_\lambda = \Phi_\lambda \circ \mathcal{P}_\lambda : \mathcal{L} \rightarrow \mathcal{F}_\lambda \) are the corresponding indexing bijections.

Certain simple spatially-periodic configurations and related states, some already mentioned in Sec. 1, will play a special role in our discussions. Let \( n^{(1)}, n^{(2)} \in \hat{X} \) be the configurations with \( n^{(1)}(i) = 1 \) and \( n^{(2)}(i) = (1) \) for all \( i \); in Sec. 1, we introduced the states \( \hat{\mu}^{(1)}, \hat{\mu}^{(2)} \in \mathcal{M}(X) \) defined by \( \hat{\mu}^{(1)} = \delta_{n^{(1)}}, \hat{\mu}^{(2)} = (\delta_{n^{(1)}} + \delta_{n^{(2)}}) / 2 \). The corresponding states \( \mu^{(1)} = \Phi_\lambda(\hat{\mu}^{(1)}), \mu^{(2)} = \Phi_\lambda(\hat{\mu}^{(2)}) \) are given by

\[
\mu^{(1)} = \frac{1}{2} \sum_{i=0}^{1} \delta_{\eta^{(1)}(i)} \quad \text{and} \quad \mu^{(2)} = \frac{3}{4} \sum_{i=0}^{1} \delta_{\eta^{(2)}(i)},
\]

where \( \eta^{(1)} \in X \) is the period-two configuration with \( \eta^{(1)}(1) = 10 \) and \( \eta^{(2)} \in X \) is the period-four configuration with \( \eta^{(2)}(1 : 4) = 1100 \). It is easy to check directly that \( \hat{\mu}^{(1)} \) and \( \hat{\mu}^{(2)} \) are ETIS states for the SSM, as are \( \mu^{(1)} \) and \( \mu^{(2)} \) for the F-SSEP.

We conclude this section with three general results; we state these for the F-SSEP, but the obvious translations to the SSM also hold. Recall from Sec. 1 that we say that a state \( \mu \in \mathcal{M}(X) \) has density \( \rho \) if it is supported on the space \( X_\rho \) [see (1.1)].

Lemma 2.4. Every ETIS state \( \mu \in \mathcal{M}(X) \) has a definite density \( \rho \) and satisfies either \( \mu(F) = 0 \) or \( \mu(F) = 1 \).

Proof. Take \( \mu \in \mathcal{M}(X) \); it suffices to show that \( \mu \) is a convex combination of states in \( \mathcal{M}(X) \) with a definite density \( \rho \) and for which \( F \) has probability 0 or 1. Let \( \nu = r_\nu |_\mu \); here, \( r : X \rightarrow \mathbb{R}, r(\eta) := \lim_{N \rightarrow \infty} (2N + 1)^{-1} \sum_{i=0}^{N} \eta(i) \), is defined \( \mu \)-almost everywhere by the ergodic theorem. \( \nu \) is just the distribution of the density with respect to \( \mu \). Then, \( \nu \) there exists a unique regular conditional probability distribution (\( \mu_\nu \)) for \( \mu \) such that \( \mu_\nu \) has density \( \rho \) and for any measurable \( A \subset X \),

\[
\mu(A) = \int_{A \subset \mu_\nu} \nu(A) d\nu(\rho).
\]

Since \( F \) is invariant under the dynamics, i.e., \( Q(\eta, F) = 1 \) for \( \eta \in F \), we see that if we further write \( \mu_\nu = \mu_\nu |_F + \mu_\nu |_{X \setminus F} \), we obtain, after normalization of \( \mu_\nu |_F \) and \( \mu_\nu |_{X \setminus F} \), the desired representation. More details are given in Ref. 10.

Lemma 2.5. Let \( \mu \in \mathcal{M}(X) \) satisfy \( \mu(F) = 0 \). Suppose that \( I \subset \mathbb{Z} \), a path measure on \( X \), and either \( |I| \geq 2 \) or \( I = \{i\} \) and \( \eta(i) = 0 \). Then, \( \nu_\mu(\{\xi \in X_2 \mid \forall t \geq 0, \xi_{i+1}(t) = \eta(i)\}) = 0 \).

We remark that the possibility \( I = \mathbb{Z}, (i) = 1 \) for all \( i \), an apparent counterexample to Lemma 2.5, is forbidden by the regularity of \( \mu \).

Proof of Lemma 2.5. Let \( A, B, C \subset X_2 \) denote the sets of space–time histories \( \xi \) such that, respectively, \( \xi_0(0) = 0 \) for all \( t \) [we write \( \xi_0(0) \equiv 0 \)], \( \xi_1(1) \equiv 0 \), and \( \xi_1(1) \equiv 1 \), and such that in each case \( \xi_1(1) \) changes infinitely often as \( t \rightarrow \infty \). We show that \( P_\mu(A) = P_\mu(B) = P_\mu(C) = 0 \); using the translation invariance of \( \mu \), translation invariance in time of \( P_\mu \), and reflection invariance of the system (although the latter is not really needed), one sees easily that this implies the result.

First, we observe that if \( \xi_0(0) = 0 \) and \( s \) is such that \( \xi_0(1) = 1 \), then, \( P_\mu(\cdot) \) is well defined on \( C \). Now, \( \xi_0(0) = 0 \) and \( \xi_1(1) = 1 \), and this is possible only if \( \xi_1(1) = 1 \). It is possible only if \( \xi_1(1) = 1, \xi_1(2) = 1 \), and so on. Thus, \( P_\mu(A) = 0 \).

Finally, we give a result showing that non-frozen TIS states cannot have too large a local density of 0’s.

Theorem 2.6. Suppose that \( \mu \in \mathcal{M}(X) \) satisfies \( \mu(F) = 0 \). Then, we have the following:

\[ \text{Lemma 2.6. Suppose that } \mu \in \mathcal{M}(X) \text{ satisfies } \mu(F) = 0. \text{ Then, we have the following:} \]
(a) \(\mu\)-a.s., no configuration contains three consecutive 0’s.
(b) \(\mu\)-a.s., the height profile \(h_0\) of the configuration \(\eta\) does not increase by more than two units over any interval.

Proof.

(a) Elementary analysis of the dynamics shows that, \(P_\rho\)-a.s., if \(\xi \in X_2\) satisfies \(\xi_t(i) = \xi_t(i+1) = \xi_t(i+2) = 0\) for some \(t, i \in \mathbb{Z}\), then also \(\xi_{t+1}(i) = \xi_{t+1}(i+1) = \xi_{t+1}(i+2) = 0\). It follows that \(\xi_t(i) = \xi_t(i+1) = \xi_t(i+2) = 0\) for all \(s \leq t\) and, by the invariance of \(P_\rho\) under time translations, for all \(s\). The conclusion follows from Lemma 2.5.

(b) Suppose that the conclusion is false. By translation invariance, we may assume that for some (necessarily odd) positive integer \(j\), \(\mu(\{j\mid h_0(j) = 3\}) > 0\), where \(A_j = \{\xi \mid h_0(j) = 3\}\). We take \(j\) to be the minimal value for which this holds. By (a), \(j > 3\), and minimality of \(j\) implies that if \(\eta \in A_j\), then a.s. \(\eta(1:j) = 00(10)^{(j-3)/2}0\). Now, by Lemma 2.5 [as in (a)], \(P_\rho(B) > 0\), where \(B = \{\xi \in X_2 \mid \xi_0 \in A_j, \xi_{-1} \in A_j\}\). On the other hand, if \(\xi \in B\), then elementary analysis shows that, \(P_\rho\)-a.s., some translate of \(\xi_{-1}\) belongs to \(A_j\), for some \(j' < j\) [for example, if \(j = 9\), then \(\xi_{-1}(1:j)\) must be one of \(1100(10)^20, 00(10)^2011, 110010011, 000111000\)]. This contradicts the minimality of \(j\).

II. LOW DENSITY

In this section, we describe all TIS states of low density (\(\rho < 1/2\) for the F-SSEP, \(\hat{\rho} < 1\) for the SSM). We first show that all ETIS states for the F-SSEP are frozen.

Lemma 3.1. Let \(\mu \in \overline{\mathcal{M}}_0(X)\) have density \(\rho < 1/2\). Then, \(\mu(F) = 1\).

Proof. By Lemma 2.4, it suffices to show that \(\mu(F) > 0\). However, if \(\mu(F) = 0\), then for any \(k > 0\),

\[
2p - 1 = \frac{1}{k} \mu \left( \sum_{i=1}^{k} (2\eta(i) - 1) \right) = \frac{1}{k} \mu(h(k)) \geq \frac{2}{k} \tag{3.1}
\]

by Lemma 2.6(b). Since \(k\) is arbitrary, \(2p - 1 \geq 0\).

To describe all low-density states, we introduce \(\mathcal{F}_{\text{low}} := \overline{\mathcal{M}}_0(F)\), the set of ETI states supported on \(F\), and \(\mathcal{F}_{\text{low}} := \overline{\mathcal{M}}_0(F)\). Since \(\mathcal{P} = \mathcal{X} = \mathcal{F}_{\text{low}} = \overline{\mathcal{M}}_0(X) = \mathcal{L}\), and thus, \(\mathcal{F}_{\text{low}}\) is indeed a \(\Lambda\)-family (see Definition 2.3), with indexing map \(\overline{\mathcal{Y}}_{\text{low}}\) the identity. One checks easily that \(\Phi_\rho(\mathcal{F}_{\text{low}}) = \mathcal{F}_{\text{low}}\) so that \(\mathcal{F}_{\text{low}}\) is also a \(\lambda\)-family, with indexing map \(\overline{\mathcal{Y}}_{\text{low}} = \Phi_\rho\). Note that \(\overline{\mu}^{(1)} \in \mathcal{F}_{\text{low}}\) has density 1 and \(\overline{\mu}^{(1)} = \Phi_\rho(\overline{\mu}^{(1)}) \in \mathcal{F}_{\text{low}}\) has density 1/2, but that otherwise the states in \(\mathcal{F}_{\text{low}}\) and \(\mathcal{F}_{\text{low}}\) have densities less than 1 or less than 1/2, respectively.

Theorem 3.2. (a) The set of ETIS states for the F-SSEP with density \(\rho < 1/2\) is \(\mathcal{F}_{\text{low}} \setminus \{\overline{\mu}^{(1)}\}\), and (b) the set of ETIS states for the SSM with density \(\hat{\rho} < 1\) is \(\mathcal{F}_{\text{low}} \setminus \{\overline{\mu}^{(1)}\}\).

Proof. For (a), note that the inclusion \(\mathcal{F}_{\text{low}} \subset \overline{\mathcal{M}}_0(X)\) is trivial, while conversely every state in \(\overline{\mathcal{M}}_0(X)\) with density less than 1/2 belongs to \(\mathcal{F}_{\text{low}}\) by Lemma 3.1. By virtue of Theorem 2.1, (b) is an immediate consequence of (a).

Finally, we ask the following question: If the F-SSEP is started in an initial state \(\mu_0\), which is a Bernoulli measure with density \(\rho < 1/2\), what is the final distribution of frozen configurations? As discussed in Remark 1.1, in earlier work, we answered this question for several other facilitated exclusion processes, finding a common limiting distribution \(\mu\). For the current model, the limit is different (see below), but beyond that we have only a partial description.

Let \(\mu_t = \mu_{t-1}Q_t\) for \(t = 1, 2, \ldots\), be the state at time \(t\), with \(\mu_0\) as above, and for \(\eta \in X\), let \(S_\eta = \{i \in \mathbb{Z} \mid \eta(i-2:i) = 000\}\).

Theorem 3.3. The limiting measure \(\mu_\infty = \lim_{t \to \infty} \mu_t\) exists and satisfies \(\mu_\infty(\{0 \in S_\eta\}) > 0\). Under the conditional measure \(\mu_\infty(\cdot \mid 0 \in S_\eta)\), \(S\) is a renewal process.

Proof. Let \(\overline{P}\) be the path measure on \(\overline{X}_2 = \{(0,1)^{\mathbb{Z} \times \mathbb{X}}\}\) obtained from the initial state \(\mu_0\) and the F-SSEP dynamics. Elementary analysis shows that if \(\xi \in X_2\) satisfies \(\xi(i-2:i) = 000\), then \(P_\rho\)-a.s. also \(\xi_{i-2:i} = 000\) for \(0 \leq s \leq t\). However, for all \(i \in \mathbb{Z}\),

\[
\begin{align*}
B_i := \{\xi \mid \xi(i-2:i) = 000 \text{ for all } t \geq 0\} \\
= \{\xi \mid \xi(i-2:i) = 000 \text{ for all sufficiently large } t\}. 
\end{align*}
\]

Moreover, \(\overline{P}(B_i) = q^2(1 - \rho)^3\), with \(q\) being the probability that for an initial measure under which the configuration on \(\mathbb{N} := \{i \in \mathbb{Z} \mid i > 0\}\) is distributed as a Bernoulli measure with density \(\rho\) but all other sites are empty, no particle crosses the \((0,1)\) bond at any time during the evolution.
Next, we show that $q > 0$. Let $A_i$ be the event that for all $L \geq 1$, there are in the configuration $\xi_t$ at most $L/2$ particles on sites $1, 2, \ldots, L$. A standard gambler’s ruin computation shows that $\mu_0(A_0) = (1 - 2q)/(1 - p)$. Now, when $A_0$ holds, no particle can cross the bond $(0, 1)$ at the next time step if the $L = 1$ condition is satisfied. Moreover, $A_i \subset A_{i+1}$. Thus, $q \geq \mu_0(A_0) > 0$.

To establish the existence of $\mu_\infty$, and, in fact, a stronger result, the $\tilde{P}$-almost sure existence of $\eta_\infty := \lim_{t \to \infty} \xi_t$, one shows from $\tilde{P}(B_i) > 0$ that for any $L > 0$, $\tilde{P}(\cup_{i \geq 1} B_i \cap B_L) = 1$. For $\xi \in B_i \cap B_L$, simple considerations of the system in a finite region then imply that $\lim_{t \to \infty} \xi_t$ exists, $\tilde{P}$-a.s. For more details, see the Proof of Lemma 3.6 of Ref. 10.

Since $\mu_{\infty}$ is the distribution of $\eta_\infty$ under $\tilde{P}$, we must show that $S_{\eta_\infty}$ is a renewal process under the conditional measure $\tilde{P}(\cdot | 0 \in S_{\eta_\infty})$. Now, from (3.2), we have that $i \in S_{\eta_\infty}$ iff $\xi_i \in B_i$, and if we condition on $0 \in S_{\eta_\infty}$, that is, on $B_0$, then what happens to the left of site $-2$ is independent of what happens to the right of site 0. Thus, if, under this conditioning, we label the points of $S_{\eta_\infty}$ sequentially as $(s_k)_{k \geq 2}$, with $s_0 = 0$, so that $\xi(s_k - 2 : s_k) = 000$ for all $t$ and $k$, the differences $s_k - s_{k-1}$ are independent.

Let us condition on $0 \in S_{\eta_\infty}$ and adopt the notation of the previous proof. Then, either $s_1 = 1$, an event with probability $1 - \rho$, or $s_1 = 4$; in the latter case, $\eta_{\infty}(-2 : s_1) = 000 \sigma 000$, with $\sigma$ being any string that begins and ends with 1 and contains no substrings 11 or 00. To complete the description of $\eta_{\infty}$, one would need to find the distribution of these $\sigma$ (and hence of $s_1 - s_0$); we have only partial results in this direction. However, one finds easily that, for example, $\mu_{\infty}(\eta(1:6) = 01101 | 0 \in S_0) = 2\rho^2(1 - \rho)^4$; on the other hand, with $\mu$ as introduced in Remark 1.1, $\mu(\eta(1:6) = 01101 | 0 \in S_0) = 2\rho^2(1 - \rho)^4$, establishing the difference of $\mu_{\infty}$ and $\mu$.

IV. DENSITIES $\rho = 1/2$ AND $\rho = 1$

In this section, we describe all ETIS states of density $1/2$ for the F-SSEP or density $1$ for the SSM. We first show that for such a state in the F-SSEP, the height profile $h_t$ [see (2.1)] is a.s. confined to a strip of height at most two. For $\eta \in X$, we let $\Delta(\eta) = \sup_{j < t}\{h_t(j) - h_t(i)\}$.

Lemma 4.1. If $\mu \in \mathcal{M}(X)$ has density $\rho = 1/2$, then $\mu$-a.s., $\Delta(\eta) \leq 2$.

Proof. By Lemma 2.4, we may assume that either $\mu(F) = 0$ or $\mu(F) = 1$. Now, $\mu^{(1)}$ is the only TI state of density $1/2$ supported on $F$, and it satisfies the conclusion of the lemma. Consider then the case $\mu(F) = 0$. By Lemma 2.6(b), $h_t(j) - h_t(i) \leq 2$ for $i < j$, so by translation invariance, it suffices to show that for any $j > 0$, $h_t(j) \geq -\mu$; moreover, it suffices to verify the result for each ergodic component of $\mu$.

Suppose then that $\mu$ is ergodic but that for some $j > 0$, $h_t(j) \geq -\mu$-a.s.; moreover, it suffices to verify the result for each ergodic component of $\mu$.

The naming of these regions reflects the fact that a configuration in which only $L$ and $T$ (respectively, $R$ and $T$) regions appear translates to the left (respectively, right) at velocity 2 under the dynamics: if $\eta_2$ is such a configuration, then $\eta_{t+1} = \tau^2 \eta_t$ (respectively, $\eta_{t+1} = \tau^2 \eta_t$). We will see below that all TIS states are supported on such configurations. The two simplest examples of such states, $\mu^{(1)}$ and $\mu^{(2)}$, were defined in (2.2); $\mu^{(1)}$ may be viewed as supported on configurations with a single $L$, or equivalently a single $R$, region, and $\mu^{(2)}$ is supported on configurations consisting of a single $T$ region.

It is straightforward to work out further rules for the evolution of the configurations with $\Delta(\eta) \leq 2$. Such configurations cannot contain the pattern $1101$, and hence, the evolution is deterministic. Boundaries between regions usually move with velocity $2$, $L$ and $T$ boundaries move to the left and $R$ and $T$ boundaries move to the right. However, if $L$ and $R$ regions are separated by a $T$ region that is a single pair of 0’s, $R[0]L$, then both boundaries are stationary. If in the resulting $T|R|00|L$ situation the $L$ region is shorter than the $R$ region, then the (left-moving) L$T$ boundary will eventually reach the 00$L$ boundary, at which time the $L$ region will disappear and the 00 and $T$ regions amalgamate into a single $T$ region; the situation is similar when the $R$ region is shorter or the two regions are the same length.

Following these ideas, one easily sees that, on a ring, any initial configuration evolves to one in which either no $L$ region or no $R$ region occurs. No such conclusion is possible when the ring is replaced by $Z$, but similar considerations do imply the following: For any configuration
η with Δ(η) ≤ 2, the minimum size δ = δ(η) of a maximal uniform block—a maximal right block, a region of the form T|R|T · · · |T|R|T preceded and followed by L regions, or a maximal left block, defined in a parallel way—must increase if δ < ∞, within a time proportional to δ. From this, it follows that any TI stationary state for ρ = 1/2 must be supported on configurations with δ = ∞, i.e., on configurations consisting of a single maximal uniform block or of a maximal right block adjacent to a maximal left block. However, the set of configurations of the latter sort must have probability 0 in any TI state.

Rather than filling in the straightforward details of the argument just sketched, we now give a different and shorter (though perhaps less intuitive) argument. Let Xleft (respectively, Xright) denote the set of configurations η ∈ X with Δ(η) = 2, which contain no R (respectively, no L) region. By convention, we suppose that Xleft and Xright contain η(1) and η(2) (see Sec. II); then, Xleft ∩ Xright consists of η(1), η(2), and their translates. Recall also the spaces Xρ, X̃ρ, Xleft, and Xright, defined in Sec. I.

**Theorem 4.2.**

(a) When ρ = 1/2, M(Xleft) = M(Xleft) ∪ M(Xright).

(b) When ρ = 1, M(̃Xρ) = M(Xleft) ∪ M(Xright).

Before giving the proof, we explain how the ETIS states of the theorem are organized into the λ-families of Definition 2.3. Consider first Mλ(X) = M(Xleft) ∪ M(Xright); here, M(Xleft) and M(Xright) are λ-families that we denote, respectively, Fleft and fright. The substitution map ϕleft : X → ̃X given by 1 → 20, 0 → 1 gives rise to an indexing bijection ̂ϕleft = Φϕleft : L → Fleft, and similarly, we obtain ̂ψright : L → Fright from ϕright, the substitution map sending 1 → 02, 0 → 1. The indexing maps for Fleft = M(Xleft) and Fright = M(Xright) are Ψleft = Φϕleft and Ψright = Φϕright or can be obtained directly from the substitution maps 1 → 1100, 0 → 10 and 1 → 0011, 0 → 01, respectively. Note that ̂Fleft ∩ ̂Fright = {ξ(1), η(2)} and Fleft ∩ Fright = {ξ(1), η(2)}.

**Proof of Theorem 4.2.**

(a) Since the F-SSEP dynamics on Xleft or Xright is simply left or right translation, respectively, clearly M(Xleft) ∪ M(Xright) ⊂ M(X).

Suppose conversely that µ ∈ M(X). Since µ is an ETIS state and Xleft and Xright are invariant under the dynamics, it suffices to prove that µ(Xleft ∩ Xright) = 1, i.e., that the set of configurations η that have Δ(η) = 2, and contain both L and R regions, has measure zero.

We first show that, µ-a.s., no configuration contains the string 010010 (corresponding to regions R|T|L with T having just two sites). Let E be the event that sites 1 and 2 both belong to an R region and that η(1 : 2) = 01. Then, from the dynamical rules,

\[
P_µ(ξ_{1 +} ∈ E) = P_µ(ξ_{1} ∈ E) - P_µ(ξ_{1} = 1101) = 010011
\]

\[
P_µ(ξ_{1} ∈ E) = P_µ(ξ_{1} = 1101) - P_µ(ξ_{1} = 0100) = P_µ(ξ_{1} = 1101 - 010010). \tag{4.1}
\]

However, µ(η(1 : 2) = 1101) = µ(η(1 : 2) = 0100), since the density of left and right ends of R regions must be the same, so that, with the stationarity of µ, (4.1) implies that µ(η(1 : 4) = 010010) = 0, as claimed.

Now, if µ(Xleft ∪ Xright) < 1, then there is a minimal k such that µ(η(1 : 4k + 6) = 0100(1100)k10) > 0. From the claim above, k > 0.

However, if ξ(1 : 4k + 6) = 0100(1100)k10, then ξ_{1 +} (3 : 4k + 4) = 0100(1100)k3−110, contradicting the minimality of k.

(b) By (a) and Theorem 2.1 (using Xleft = X̃ρ and Xright = X̃ρ), we have

\[
M_λ(X) = Φk(1) (M_λ(Xleft/2)) = Φ_k(1) (M(Xleft)) ∪ Φ_k(1) (M(Xright)) = M(Xleft) ∪ M(Xright). \tag{4.2}
\]

**V. HIGH DENSITY**

Most of our discussion of the high density region, ρ > 1/2 for the F-SSEP or ρ > 1 for the SSM, will be carried out for the SSM. We first obtain a reduction of the configuration space of the model to the space X̃* < X, the set of configurations for which no two adjacent sites both have short stacks (see Sec. I). Note that any extremal TI state in X̃* must have density ρ̃e satisfying ρ̃e ≥ 1. For future reference, we also note that H := Φ(X̃*) is the set of F-SSEP configurations that do not contain any of the substrings 000, 0100, 010, and 0101.

**Theorem 5.1.** Every TIS state for the stack dynamics with density ρ > 1 is supported on X̃*; equivalently, every TIS state for the F-SSEP dynamics with density ρ > 1/2 is supported on H.
Proof. It is convenient to work primarily in the stack model. We observe first that since 00 in the stack model corresponds to 000 in the F-SSEP model, Lemma 2.6 implies that every \( \hat{\mu} \in \mathcal{M}_t(\hat{X}) \) with density \( \hat{p} > 1 \) assigns zero probability to the set of all configurations containing the substring 00.

Now, we suppose that \( \hat{\mu} \in \mathcal{M}_t(\hat{X}) \) has density \( \hat{p} > 1 \) and is such that configurations containing the string 10 occur with nonzero probability under \( \hat{\mu} \), and derive a contradiction; we may assume that \( \hat{\mu} \) is ergodic. For \((t, i) \in \mathbb{Z}^2\), let \( E_{t, i} \subset \hat{X}_t^2 \) be the event that \( m \in E_{t, i} \) satisfies \( m_t(i : i + 1) = 10 \); then, for \( m \in E_{t, i} \), we know from Lemma 2.5 that there must a.s. exist times \( t_0 \) and \( t_1 \), with \( t_0 < t_1 \), such that \( m \in E_{t, i} \) for \( t_0 < t < t_1 \) but \( m \notin E_{t_0 - 1, i} \) and \( m \notin E_{t_1, i} \). Then, elementary consideration of the dynamics, using the fact the 00 does not occur, shows that necessarily \( m_{t, i-1} \) is 10, i.e., the string 10 cannot be "created" at sites \((i, i + 1)\) but rather "moves" there from sites \((i - 1, i)\). However, such a string cannot vanish, since \( \hat{\mu} \) is stationary and, hence, the density of 10 strings is constant in time, and again simple considerations show that necessarily \( m_{t, i-1}(i : i + 2) = 102 \) and \( m_t(i + 1 : i + 2) = 10 \). The conclusion is that, P.a.s., 10 substrings persist throughout time, moving to the right in the sense that there exist times \( t_0 < t_1 < t_2 < \cdots \) such that \( m_t(i + k : i + k + 1) = 10 \) for \( t_0 < t < t_k + 1 \).

A similar analysis applies to 01 strings, except that these move to the left. However, we claim that \( \hat{\mu} \) supports a positive density of 10 substrings but that, \( \hat{\mu} \)-a.s., 01 strings do not occur. However, the state \( \hat{\mu} \) is supported on \( X^* \) and, hence, is ergodic but not weakly mixing. For \( \hat{\mu} \)-a.s., the string 11 cannot occur in \( X^* \). To complete the proof, we must show that, \( \hat{\mu} \)-a.s., the string 11 cannot occur in \( X^* \). However, as for the initial analysis of 10 above, if \( m \in \hat{X}_t \) satisfies \( m_t(i : i + 1) = 11 \), then, P.a.s., there must be a time \( t_0 \leq t \) with \( m_t(i : i + 1) = 11 \) but \( m_{t_0 - 1}(i : i + 1) = 11 \), and it is easy to see by considering various possible values of \( m_{t_0 - 1}(i : i + 1) \) that this cannot happen.

In the remainder of Sec. V, we study the ETIS states of the SSM considered as a process with state space \( \hat{X}^* \). Theorem 5.1 justifies this choice for states with density \( \hat{p} > 1 \). Moreover, the state \( \hat{\mu}^{(2)} \) introduced in Sec. I was shown in Sec. IV to be an ETIS state of density \( \hat{p} = 1 \) for the SSM; \( \hat{\mu}^{(2)} \) is supported on \( \hat{X}^* \) (and is the only such state). It is convenient to include this state in our study so that from now on, we assume that \( \hat{p} > 1 \).

The dynamical rules of the SSM simplify on \( \hat{X}^* \) as follows: if \( n(i) = 0 \) or 1, then in the transition to \( n_t \), a particle moves from each of the sites \( i + 1 \) and \( i - 1 \) to \( i \), while if \( n(i) = 2 \), then a particle moves from \( j + 1 \) to \( j \) or \( j \) to \( j - 1 \), with each probability 1/2. Since at each time step a particle must move across each bond, the parity \((-1)^{n(0)}\) of the stack height at each site \( i \) is conserved. Let \( S := \{0, 1\}^\mathbb{Z} \) be the space of parity sequences, define the parity map \( P : \hat{X}^* \to S \) by \( P(n)(i) = (1 + (-1)^{n(0)})/2 \), and for \( \sigma \in S \), define the parity sector \( X^*_\sigma \subset \hat{X}^* \) by \( X^*_\sigma := P^{-1}(\sigma) \) for all \( \sigma \) in \( S \) if, for all \( i \), \( n(i) \) and \( \sigma(i) \) have the same parity.

Since for each \( \sigma \in S \) the parity sector \( X^*_\sigma \) is invariant under the dynamics, we obtain by restriction a dynamical system on each \( X^*_\sigma \). In Sec. V A, we discuss the stationary states in the even sector \( X^*_{e} \), where \( e \) is the parity sequence satisfying \( e(i) = 0 \) for all \( i \), and in Sec. V B and Appendix B, we show how these give rise to all the ETIS states on \( \hat{X}^* \).

A. ETIS states in the even sector

Our next result describes a family of ETIS states for the SSM in the even sector; the proof will be given shortly.

Theorem 5.2. For each \( \hat{p}_e \geq 1 \), there is an ETIS state \( \mu^{(e)} \) on \( X^*_e \) of density \( \hat{p}_e \); \( \mu^{(e)} \) is a grand-canonical Gibbs state for the statistical-mechanical system with state space \( \hat{X}^*_e \) and one-body potential

\[
V(n) := 2 \ln 2 \delta_{n,0},
\]  

(5.1)
As we will see in Sec. V B and Appendix B, for a full discussion of the ETIS states of the SSM on \( \mathbb{X}_e \), we need to know all stationary states on \( \mathbb{X}_e \), both TI and non-TI (should any of the latter exist). We have the following conjecture:

**Conjecture 5.3.** For each \( \rho_e \geq 1 \), \( \mu_{\rho_e}^{(0)} \) is the unique stationary state of the SSM on \( \mathbb{X}_e \) with density \( \rho_e \).

In Sec. V B, we will discuss the ETIS states on \( \mathbb{X}_e \) under the assumption that Conjecture 5.3 holds, and in Appendix B, we turn to the general case.

We begin our discussion of Theorem 5.2 with the consideration of the SSM on a ring of \( 2L + 1 \) sites, indexed by \( I_L := \{-L, \ldots, L\} \); the configuration space \( \mathbb{X}_e^{(L)} \) is the set of elements \( n \in \mathbb{Z}_L^2 \) for which \( n(i) \) is even for all \( i \) and for which no two adjacent sites both have height zero. For the moment, we take a fixed number \( N \) of particles, with \( N \) even and \( N \geq 2L + 2 \), with the corresponding configuration space \( \mathbb{X}_e^{(L),N} \subset \mathbb{X}_e^{(L)} \). For \( n \in \mathbb{X}_e^{(L),N} \), let \( z(n) \) be the number of sites \( i \) with \( n(i) = 0 \). In a transition from \( n \) to \( n + 1 \), the direction of particle movement across \( z(n) \) bonds is determined and across the remainder is chosen randomly; moreover, a given transition can occur via at most one set of these choices unless \( n \sim n + 1 \), in which case there are two possibilities [this occurs iff \( z(n) = 0 \)]. Thus, the probability \( P(n, n + 1) \) of such a transition, if nonzero, is \( 2^{-2L+2} z(n)+1 \). Then, a TIS state \( \mu^{(N,L)} \) is given by \( \mu^{(N,L)}(n) = \mathbb{Z}_L^2 2^{-2\lambda(n)} \), with \( \mathbb{Z}_L^2 \) a normalizing constant, since because \( P(n, n + 1) = 0 \卯 P(n', n) = 0 \), \( \mu^{(N,L)} \) satisfies the detailed balance condition \( \mu^{(N,L)}(n) P(n', n) = \mu^{(N,L)}(n') P(n', n) \). It is straightforward to check that the dynamics permits transition from any configuration in \( \mathbb{X}_e^{(N,L)} \) to any other so that \( \mu^{(N,L)} \) is the unique TIS state.

The state \( \mu^{(N,L)} \) is a Gibbs measure arising from the one-particle potential \( V(n) \) of (5.1), that is, \( \mu^{(N,L)}(n) = \mathbb{Z}_L^2 \prod_{i \in \mathbb{Z}_L^2} e^{-V(n(i))} \). (One may also view \( \mu^{(N,L)} \) as a Gibbs measure on the space of all \( \Lambda \)-particle configurations, with one- and two-body hard core potentials, that is, formal potentials taking infinite values, that impose the restrictions of \( \mathbb{X}_e^{(L)} \).) In order to pass to the \( L \to \infty \) limit it is convenient to consider the grand canonical measure with fugacity \( \zeta \geq 0 \):

\[
\mu^{(\zeta,L)} = \mathbb{Z}_L^2 \sum_{n \in \mathbb{X}_e^{(L)}} \zeta^{n(i) - 2L - 2} e^{\zeta V(n(i))},
\]

with \( \mathbb{Z}_L^2 \) again a normalizing constant.

**Lemma 5.4.** The limiting measure \( \mu^{(\zeta,\infty)} = \lim_{L \to \infty} \mu^{(\zeta,L)} \) exists for \( 0 \leq \zeta < 1 \) and is a TIS state of density \( 1/(1 - \zeta) \) for the SSM on \( \mathbb{X}_e \). Moreover, \( \mu^{(0,\infty)} = \mu^{(2)} \) and \( \mu^{(\zeta,\infty)} \) is mixing if \( \zeta > 1 \).

**Proof.** The case \( \zeta = 0 \) follows immediately from the fact, evident from (5.2), that \( \mu^{(0,L)} \) gives equal weight to the \( 2L + 1 \) configurations in \( \mathbb{X}_e^{(N,L)} \) with \( \sum_i n(i) = 2L + 2 \). From now on, we assume that \( 0 < \zeta < 1 \).

We can prove the existence of \( \mu^{(\zeta,\infty)} \), and also calculate many of its properties, using the standard transfer matrix formalism; we give only a sketch. Let us think of \( \mathbb{L} = \{x_i\}_{i \in \mathbb{Z}} \) as a space of column vectors, with \( u^T \) denoting the transpose of the vector \( u \), and define \( u, v \in \mathbb{L} \) by \( u_i = \delta_0 \) and \( v_0 = 0 \), \( v_i = \zeta^i \) if \( i \geq 1 \). Then, for \( n = 2i \in \mathbb{X}_e^{(L)} \),

\[
\mu^{(\zeta,L)}(n) = \mathbb{Z}_L^2 \prod_{i \in \mathbb{Z}_L^2} T_{(i-1)2L+(i+1)2L} \cdots T_{(i-1)2L+i} T_{(i)L}(i) T_{(i)L}(-i),
\]

with \( \mathbb{Z}_L^2 \) being the trace of \( \mathbb{T}^{2L+1} \). \( \mathbb{T} \) is a rank 2 operator with nonzero eigenvalues \( \lambda_1 = \zeta/(2(1 - \zeta)) \) and \( \lambda_2 = -(1 + \zeta)/(2(1 + \zeta)) \); the eigenvector associated with \( \lambda_1 \), the larger in magnitude, is \( w = \zeta/(1 + \zeta) u + v \) so that

\[
\lim_{n \to \infty} \lambda_1^n w = \|w\|^2 w^T w.
\]

Thus, for \( m = 2i \in \mathbb{X}_e^{(L)} \) and \( E \) the event that \( n(-K : K) = m(-K : K) \), we have

\[
\mu^{(\zeta,\infty)}(E) = \lim_{L \to \infty} \mu^{(\zeta,L)}(E) = \mathbb{Y}_{\zeta,K \uparrow\downarrow \uparrow} \mathbb{T}_{(-K)(-K+1)} \cdots \mathbb{T}_{(K)(K+1)} w^T w,
\]

with

\[
\mathbb{Y}_{\zeta,K} = \lambda_1^{2K} \|w\|^2 = \frac{\zeta^{2K+2}}{(1 + \zeta)^{2K+1} (1 - \zeta)^{2K+1}}.
\]
Taking $K = 0$ in (5.5), we find that
\[
\mu^{(\infty)}(\mathbf{n}(0) = 2l) = \gamma^{-1}_{\infty}(\mathbf{n})^2 = \begin{cases} 
(1 - \zeta)/2, & \text{if } l = 0, \\
(1 + \zeta)^2(1 - \zeta)^{2l+2}/2, & \text{otherwise},
\end{cases}
\] (5.7)
from which we find the density $\hat{\rho}(\zeta) := \mu^{(\infty)}(\mathbf{n}(0)) = 1/(1 - \zeta)$. From (5.4) and (5.5), it follows that if $f, g : \mathbb{X}^* \to \mathbb{R}$ each depend only on the values of the configuration at a finite number of sites, then $\mu^{(\infty)}(f \circ g) \sim C_{e}(1 - |k|)^n$ as $n \to \infty$, so that $\mu^{(\infty)}$ is mixing.

The stationarity of $\mu^{(\infty)}$ can be verified from the explicit formulas (5.5) and (5.6), but it is simpler to argue from the stationarity of $\mu^{(L)}$. Take $L > K > 0$, suppose that $A^{(K)} \subset \mathbb{X}_e^{(K)}$, and let $A$, respectively, $A^e$, be the set of $n \in \mathbb{X}_e^*$, respectively $n \in \mathbb{X}_e^{(L)}$, such that $n(-K - 1 : K + 1) \in A^{(K)}$. If $Q$ and $Q^{(L)}$ are the transition kernels for the SSM on $\mathbb{X}^*$ and $\mathbb{X}^{(L)}$, respectively, then the stationarity of $\mu^{(L)}$ implies that
\[
\int_{\mathbb{X}^*} Q^{(L)}(\mathbf{n}, A^{(L)}) \mu^{(L)}(d\mathbf{n}) = \mu^{(L)}(A^{(L)}).
\] (5.8)
Now, $Q^{(L)}(\mathbf{n}, A^{(L)})$ depends only on $n(-K - 1 : K + 1)$ and $Q^{(L)}(\mathbf{n}, A^{(L)}) = Q(n', A)$ if $n(-K - 1 : K + 1) = n'(-K - 1 : K + 1)$ so that taking the $L \to \infty$ limit in (5.8) yields $\int_{\mathbb{X}^*} Q(\mathbf{n}, A) \mu^{(\infty)}(d\mathbf{n}) = \mu^{(\infty)}(A)$, the stationarity of $\mu^{(\infty)}$.

Proof of Theorem 5.2. The theorem follows immediately from Lemma 5.4 via $\sigma^{(\infty)} = v^{(\infty)}(\hat{\rho}_{\infty})$.

Remark 5.5. There is an alternative way to describe the state $\mu^{(\infty)}$ (and hence also $\mu^{(L)}$). Consider the image of $\mu^{(\infty)}$ under the map $F : \mathbb{X}^* \to \{0, 1\}^\mathbb{Z}$ defined by $F(\mathbf{n}(j) = \min(1, \mathbf{n}(j)))$, which effectively classes sites simply as occupied or empty. The image measure $F_\ast \mu^{(\infty)}$ is again Gibbsian, with no interactions other than the exclusion of configurations containing adjacent holes, so that it is, after an interchange of the roles of particles and holes, the equilibrium state of the familiar nearest-neighbor hard core model. The holes in this system have effective fugacity $(1 - \zeta^2)/(2\zeta^2)$ relative to a fugacity of 1 for the particles, and from (5.7), the density of holes is $(1 - \zeta)/2$. The full state $\mu^{(\infty)}$ is then obtained by first conditioning $F(\mathbf{n}) = \eta$ for some $\eta \in \{0, 1\}^\mathbb{Z}$ with no adjacent holes, distributed according to $F_\ast \mu^{(\infty)}$, and then distributing particles on each site $j$ for which $\eta(j) = 1$ independently, with distribution $\mu(\mathbf{n}(j) = 2l) = \zeta^{2l+1}/(1 - \zeta^2)$, $l = 1, 2, \ldots$.

B. ETIS states for the SSM

We now discuss the passage from stationary states of the SSM on the even sector to general high-density ETIS states, specifically, to states with $\hat{\rho} > 1$ as well as the special state $\mu^{(2)}$ with $\hat{\rho} = 1$. By Theorem 5.1, these are precisely the ETIS states on $\mathbb{X}_e^*$. Let us define $\gamma : \mathbb{X}_e^* \times \mathbb{S} \to \mathbb{X}_e^*$ by $\gamma(m, \sigma) = m + \sigma$ [with component-wise addition: $(m + \sigma)(i) := m(i) + \sigma(i)$]. Note that for fixed $\sigma \in \mathbb{S}$, $\gamma(\cdot, \sigma)$ is a bijection of $\mathbb{X}_e^*$ with $\mathbb{X}_e^*$. We define the dynamics in $\mathbb{X}_e^* \times \mathbb{S}$ to be constant on $\mathbb{S}$.

Lemma 5.6.
(a) A measure $\mu$ on $\mathbb{X}_e^*$ is an ETIS state for the SSM iff $\tilde{\mu} := \gamma^{-1}_e \mu$ is an ETIS state on $\mathbb{X}_e^* \times \mathbb{S}$.
(b) Each ETIS state $\tilde{\mu}$ of density $\hat{\rho}$ on $\mathbb{X}_e^* \times \mathbb{S}$ has the form $\mu(\mathbf{d}n \, d\sigma) = \mu_\sigma(\mathbf{d}n)\lambda(d\sigma)$, where $\lambda$ is an ergodic TI probability measure on $\mathbb{S}$ and $\mu_\sigma, \sigma \in \mathbb{S}$ are stationary probability measures on $\mathbb{X}_e^*$ satisfying $\mu_\sigma = \tau_\sigma \mu_\sigma$. Moreover, if $\lambda$ has density $\kappa$, then $\lambda$-almost all $\mu_\sigma$ have density $\hat{\rho}_\sigma = \hat{\rho} - \kappa$.

Proof.
(a) The map $\gamma$ clearly commutes with translations and with the dynamics. Thus, $\gamma_e$ and $\gamma^{-1}_e$ carry TIS states to TIS states, and they clearly preserve extremality.
(b) The form $\mu(\mathbf{d}n \, d\sigma) = \mu_\sigma(\mathbf{d}n)\lambda(d\sigma)$ is immediate, with $\lambda$ being the probability measure on $\mathbb{S}$ giving the distribution of $\sigma$ and $\mu_\sigma$ being the conditional probability measure on $\mathbb{X}_e^*$, given $\sigma$. The stationarity of $\tilde{\mu}$ implies the stationarity of each $\mu_\sigma$, and the translation invariance of $\hat{\rho}$ yields the translation invariance of $\lambda$ and the relation $\mu_\sigma = \tau_\sigma \mu_\sigma$. $\lambda$ must be ergodic, since a decomposition of $\lambda$ as a convex combination of TI measures would yield immediately a decomposition of $\mu$ in terms of TIS measures. Finally, since $\lambda$-a.s. configurations have density $\hat{\rho}_\sigma = \hat{\rho} - \kappa$.

Throughout the remainder of this section, we assume that Conjecture 5.3 holds. See Appendix B for an analysis of the situation when this assumption is not valid.

Theorem 5.7. Suppose that $\mu^{(\infty)}$ of Theorem 5.2 are the only stationary states of the SSM on $\mathbb{X}_e^*$, i.e., that Conjecture 5.3 holds. Then, the ETIS states with density $\hat{\rho} > 1$ are precisely the states $\mu^{(\hat{\rho})} := \gamma_e(\mu^{(\infty)} \times \lambda)$, with $\lambda$ being an ergodic TI probability measure on $\mathbb{S}$ of density $\kappa \leq \hat{\rho} - 1$ and $\rho_\sigma = \hat{\rho} - \kappa$. 

Before giving the proof, we note an immediate consequence of this result and Theorem 2.1.

Corollary 5.8. Under the hypotheses of Theorem 5.7, the ETIS states of the F-SSEP with density \( \rho > 1/2 \) are the states \( \Phi_\delta(\mu^{(L)}) = \mu^{(L)} \) has density \( \hat{\rho}/(1 + \hat{\rho}) \).

Proof of Theorem 5.7. By Lemma 5.6, it suffices to prove that the ETIS states on \( \hat{X}_e^* \times S \) are the states \( \mu^{(L)} \times \lambda \) described in the theorem.

Remark 5.9.

(a) The states \( \mu^{(L)} \) of the SSM with \( \hat{\rho} > 1 \) are defined in Theorem 5.7; it is natural then to define also \( \mu^{(L,\kappa)} := \gamma_e(\mu^{(L)} \times \delta_\kappa) = \mu^{(2)} \), with \( \delta_\kappa \in \mathcal{M}(S) \) the point mass on the zero configuration \( e \).

(b) It follows from the theorem that, whenever \( \mu^{(L,\kappa)} \) is defined, the density \( \kappa \) of the measure \( \lambda \) satisfies \( 0 \leq \kappa \leq \max\{1 - \hat{\rho}, 1\}. \) The case \( \hat{\rho} = 1 + \kappa \), corresponding, in the notation of the theorem, to \( \hat{\rho}_e = 1 \), is of particular interest; see (c) and (d).

(c) \( \mu^{(L,\kappa)} \) is extremal in the class of TIS states, but it may not be ergodic under translations. For example, if \( \sigma \in S \) has even period \( p \) and density \( \kappa \), and \( \lambda \) is the superposition of the point masses on \( \sigma \) and its translates, then if \( \hat{\rho} = 1 + \kappa \) (i.e., if \( \hat{\rho}_e = 1 \)), \( \mu^{(L,\kappa)} \) is a superposition of two ergodic measures, these being the superpositions of the translates of \( \mathfrak{n}^+ \sigma \) and \( \mathfrak{m}^+ \sigma \), respectively. When, in general, can such non-ergodicity occur? First, if \( \hat{\rho}_e > 1 \), then \( \mu^{(L,\kappa)} \) is the product of a mixing and an ergodic measure, is ergodic, and hence so is \( \mu^{(L,\kappa)} \). On the other hand, if \( \hat{\rho}_e = 1 \), we use the fact that \( \mu^{(L,\kappa)} \) is ergodic if the eigenvalue 1 of the translation operator in \( L^2(\hat{X}_e^* \times S, \mu^{(L,\kappa)} \times \lambda) \) is simple; since the translation on \( \hat{X}_e \times S \) has simple eigenvalues of \( \pm 1 \) and no others, we conclude that \( \mu^{(L,\kappa)} \) is ergodic iff the translation operator on \( L^2(S, \lambda) \) does not have the eigenvalue \(-1\).

(d) If \( \lambda \) has density \( \kappa \), then, \( \mu^{(1+\kappa)} \)-a.s., each configuration \( \mathfrak{n} \) has sites with \( 0 \) or \( 1 \) particle(s) alternating with sites with \( 2 \) or \( 3 \) particles, and the dynamics carries such a configuration to the one obtained from it by the substitutions \( 0 \to 2, 1 \to 3, 2 \to 0, \) and \( 3 \to 1 \). The evolution of these configurations is thus periodic, of period 2.

We finally observe that the states \( \mu^{(L,\kappa)} \) for fixed \( \hat{\rho}_e = \hat{\rho} - \kappa \) (where as usual \( \kappa \) is the density of \( \lambda \)) form a \( \lambda \)-family (see Definition 2.3), which we denote \( \mathcal{F}_\kappa \). The indexing map \( \Psi_\kappa : \mathcal{L} \to \mathcal{F}_\kappa \) is given by \( \Psi_\kappa(\lambda) = \mu^{(L,\kappa)} \), where we have made the identification \( \mathcal{L} = \mathcal{M}(S) \). From Corollary 5.8, then, the ETIS states of the F-SSEP with density \( \rho > 1/2 \), together with the state \( \mu^{(2)} \), form the \( \lambda \)-families \( \mathcal{F}_\kappa = \Phi_\kappa(\mathcal{F}_\kappa) \).

VI. SUMMARY

The results of this paper are summarized, under the assumption that Conjecture 5.3 holds, by Fig. 2, which gives a symbolic depiction of the relations among the \( \lambda \)-families of regular ETIS states of the SSM. The heavy black lines denote \( \lambda \)-families. \( \mathcal{F}_\text{left} \) and \( \mathcal{F}_\text{right} \) have been separated for visibility, but, in fact, both lie at \( \hat{\rho} = 1 \). The state \( \mu^{(1)} \) belongs to all three of the families \( \mathcal{F}_\text{left}, \mathcal{F}_\text{right} \), and \( \mathcal{F}_\text{right} \), and the state \( \mu^{(2)} \) belongs to \( \mathcal{F}_\text{left} \) and \( \mathcal{F}_\text{right} \) in Remark 5.9). \( \kappa \) denotes the density of a measure \( \lambda \in \mathcal{M}(S) \); this variable is relevant only for the state \( \mu^{(2)} \) (for which \( \kappa = 0 \)) and for states with \( \hat{\rho} > 1 \). The shaded region is filled with the \( \lambda \)-families \( \mathcal{F}_\kappa \); for \( \hat{\rho}_e = 1 \) and three other representative families (\( \hat{\rho}_e = r_1, r_2, r_3 \)) are shown.

FIG. 2. Symbolic picture of the set of ETIS states of the SSM. The heavy black lines denote \( \lambda \)-families; the shaded region is filled with these families. See Sec. VI for a full description.
DEDICATION

This paper is dedicated to the memory of Freeman Dyson, friend and teacher.

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AUTHOR DECLARATIONS

Conflict of Interest

The authors have no conflicts to disclose.

Author Contributions

S. Goldstein: Formal analysis (equal); Investigation (equal); Writing – original draft (equal); Writing – review & editing (equal).
J. L. Lebowitz: Formal analysis (equal); Investigation (equal); Writing – original draft (equal); Writing – review & editing (equal).
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DATA AVAILABILITY

Data sharing is not applicable to this article as no new data were created or analyzed in this study.

APPENDIX A: EQUIVALENCE OF TIME MEASURES UNDER SUBSTITUTIONS

In this appendix, we give a construction that will be used at several points in this paper. Suppose that $S$ and $T$ are countable alphabets, that $\hat{Y} = S^\mathbb{Z}$ and $Y = T^\mathbb{Z}$ with typical elements $\zeta \in \hat{Y}$ and $\eta \in Y$, and that for each $s \in S$, we specify a finite sequence $\chi(s) = t_1(1) \ldots t_k(s)$ of elements of $T$ (that is, a word of $k(s)$ letters in the alphabet $T$). Then, we define $\phi : \hat{Y} \to Y$ to be the map that substitutes $\chi(s)$ for $s$, that is,

$$ \phi(\zeta) = \chi(0)\chi(1)\chi(2) \ldots = \chi(\zeta(1))\chi(\zeta(0))\chi(\zeta(1))\chi(\zeta(1))\ldots, $$

(A1)

with $\chi(\zeta(1))$ beginning at site 1, so that $\phi(\zeta(1)) = t_{\zeta(1)}(1)$. For $s \in S$, we define $\hat{Y}_s = \{ \zeta \in \hat{Y} | \chi(1) = s \}$ and $Y_s = \phi(\hat{Y}_s)$; for $0 \leq j \leq k(s) - 1$, we set $Y_{sj} = \tau^j Y_s$ and define $\phi_{sj} : \hat{Y}_s \to Y_{sj}$ by $\phi_{sj} = \tau^j \phi|_{\hat{Y}_s}$. From now on, we assume that the $\chi(s)$ are such that the sets $Y_{sj}$ are pairwise disjoint.

We call a TI measure $\nu$ on $\hat{Y}$ regular if $\nu(k(\zeta(1)))$ is finite, i.e., if $Z_0 = \sum_{s \in S} k(s) \nu(Y_s) < \infty$, and a TI measure $v$ on $Y$ regular if it is supported on $\bigcup_{s \in S} \bigcup_{j=0}^{k(s)-1} Y_{sj}$, the smallest translation invariant subset of $T^\mathbb{Z}$ containing $\phi(\hat{Y})$. Let $\mathcal{M}(\hat{Y})$ denote the space of regular TI states on $\hat{Y}$ and $\mathcal{M}(Y)$ denote the space of regular TI states on $Y$.

**Theorem A.1.** For $\hat{v} \in \mathcal{M}(\hat{Y})$, define the measure $\Phi(\hat{v})$ on $Y$ by

$$ \Phi(\hat{v}) := Z_v^{-1} \sum_{s \in S} \sum_{j=0}^{k(s)-1} \nu_{sj} \hat{v}_s, $$

(A2)

Then, $\Phi$ is a bijection of $\mathcal{M}(\hat{Y})$ with $\mathcal{M}(Y)$, and for $v \in \mathcal{M}(Y)$, $\Phi^{-1}(v) = \tilde{Z}_v^{-1} \sum_{s \in S} \phi^{-1}_{sj} \nu_s$, where $Z_v = \sum_{s \in S} \nu(Y_s)$. $\Phi(\hat{v})$ is ergodic iff $\hat{v}$ is.

**Proof.** This is straightforward to check. The final statement follows from the fact that $\hat{v} = \sum c_s \hat{v}_s$ if and only if $\Phi(\hat{v}) = \sum c_s \Phi(\hat{v}_s)$, where $\hat{v}_s \in \mathcal{M}(\hat{Y})$ and $c_s = Z_{\hat{v}} c_s / Z_v$.

We now suppose that we are given dynamical rules in the spaces $\hat{Y}$ and $Y$, that is, translation invariant Markov processes with state spaces $\hat{Y}$ and $Y$, specified by respective TI transition kernels $Q(\zeta, A)$ and $Q(\eta, B)$. We will say that $Q$ or $P$ preserves ergodicity if $\nu Q$ (respectively, $\nu P$) is ergodic whenever $\nu$ (respectively, $\nu$) is; preserving regularity is defined similarly.

We next want to give a condition which will imply that the mapping $\Phi$ preserves these dynamics, i.e., that $\Phi(\nu Q) = \Phi(\nu) Q$; we will need some further notation. Let $\hat{Y} \times Y$ be the set of pairs $(\zeta, \eta)$ such that $\eta$ is a (possibly trivial) translate of $\phi(\zeta)$, and let $\hat{\eta}$ and $\eta$ be the projections of $\hat{Y}$ onto the first and second components, respectively, of $\hat{Y} \times Y$.

**Definition A.2.** A $\tau$-coupling of $Q$ and $P$ is a Markov transition kernel $\bar{Q}$ with state space $\hat{Y}$ such that for $(\zeta, \eta) \in \hat{Y}$, $\zeta \subset \hat{Y}$, and $A \subset Y$,

$$ \bar{Q}(\zeta, \eta, \tau^{-1}(A)) = \bar{Q}(\zeta, \bar{A}), $$

(A3)

$$ \bar{Q}(\zeta, \eta, \tau^{-1}(A)) = Q(\eta, A). $$

(A4)
Equivalently, a Markov transition kernel $\mathcal{Q}$ with state space $Y$ is a $τ$-coupling of $\mathcal{Q}$ and $Q$, provided that for any Markov process $(\xi, \eta)$ with the transition kernel $\mathcal{Q}$, $\xi$ and $\eta$ are Markov processes with transition kernels $\mathcal{Q}$ and $Q$, respectively.

Remark A.3. To show that there is a $τ$-coupling of $\mathcal{Q}$ and $\mathcal{Q}$, it suffices to find a restricted transition probability $\mathcal{Q}(\xi, \phi(\xi), \cdot)$, which satisfies (A3) and (A4) when $\eta = \phi(\xi)$. $\mathcal{Q}$ can then be extended to the rest of $Y$ by setting $\mathcal{Q}(\xi, \eta, \cdot) := \mathcal{Q}(\xi, \phi(\xi), \cdot)$ when $\eta = r^\ast \phi(\xi)$, choosing $q$ when periodicity of $\phi(\xi)$ necessitates a choice, to be the minimal non-negative $q$ with $\eta = r^\ast \phi(\xi)$. Here, $\tau$ acts on $Y$ via $\tau(\xi, \eta) := (\xi, r^\ast \eta)$.

Theorem A.4. Suppose that $Q$ and $\mathcal{Q}$ are TI Markov transition kernels on $Y$ and $\mathcal{Y}$, respectively, which preserve ergodicity and regularity and for which there exists a $τ$-coupling $\mathcal{Q}$. Then, for any TI state $\nu \in M(\mathcal{Y})$ and any $n \geq 1$, $\Phi(\nu)^n = \mathcal{Q}(\nu)$.

Corollary A.5. If $Q$ and $\mathcal{Q}$ are as in Theorem A.4, then $\Phi$ is a bijection of $M(\mathcal{Y})$ with $M(Y)$, i.e., $\nu \in M(\mathcal{Y})$ is stationary for $\mathcal{Q}$ if and only if $\Phi(\nu)$ is stationary for $Q$.

The corollary is, of course, immediate. The idea of the Proof of Theorem A.4 is taken from Refs. 10 and 12:

Proof of Theorem A.4. It suffices to verify the result for $\nu$ ergodic. Then, since $\mathcal{Q}$ and $Q$ preserve ergodicity, as does $\Phi$, $\nu(\mathcal{Q})$ and $\Phi(\nu)$ are ergodic, so that these two measures are either equal or mutually singular. Hence, to prove their equality, it suffices to find a nonzero measure $\lambda$ with $\lambda \leq \Phi(\nu)^0$ and $\lambda \leq \Phi(\nu)^0$.

Let $\mathcal{Q}$ be a $τ$-coupling of $\mathcal{Q}$ and $Q$ with state space $\mathcal{Y}$, as in Definition A.2, define $\psi : \mathcal{Y} \to Y$ by $\psi(\zeta) := (\zeta, \phi(\zeta))$, and for $\nu \in M(\mathcal{Y})$, let $\nu' := \nu \circ \psi$, so that $\pi_\nu = \pi_\nu$ and $\pi_\nu = \pi_\nu$. Fix $n \geq 1$, and let $\nu \in Y$ be such that $(\Phi(\nu)^n)(C_{q}) > 0$, where $C_{q} := \{(\zeta, \eta) \in Y | \eta = \tau^q(\phi(\zeta))\}$, and define $C_{q} = 1_{C_{q}}(\nu') = \nu' \circ \pi_\nu$ and $C_{q} = \nu' \circ \pi_\nu$. We claim that $\nu'' = \nu' \circ \pi_\nu$ and that, for an appropriate constant $c > 0$, (ii) $cv' \leq \Phi(\nu'^n)$ and (iii) $cv'' \leq \Phi(\nu'^n)$.

It remains to prove the claim. (i) follows from the definition of $C_{q}$. From Definition A.2, $\pi_\nu(\nu') = \pi_\nu(\nu'^n)$ and $\pi_\nu(\nu'^n) = (\phi(\nu'), \nu'^n)$, and with this and (A2), we have

$$v' = \phi_\nu \pi_\nu(\nu'^n) = \phi_\nu(\nu'^n) = Z_{0} \Phi(\nu')$$

and

$$v'' = \pi_\nu(\nu'^n) = \phi_\nu(\nu'^n) = Z_{0} \Phi(\nu')$$

This verifies parts (ii) and (iii) of the claim, with $c := \min\{Z_{0}^{-1}, Z_{0}^{-1}\}$.

In the remainder of this appendix, we discuss the applications we make of these results. Theorem A.1 is used in Sec. IV; the substitution maps there are denoted $\phi_{\text{left}}$ and $\phi_{\text{right}}$. Theorems A.1 and A.4 are used to obtain a correspondence between the stationary states of the Symmetric Markov Model (SSM) and of the Facilitated Simple Symmetric Exclusion Process (F-SSEP), a correspondence first introduced in Sec. I, that section and Sec. II for the definition of the transition kernels $\mathcal{Q}$ and $Q$ for these models) and used throughout this paper. In this application, $S = \mathbb{Z}$, $T = \{0, 1\}$, and for $n \in \mathbb{Z}$, $\chi(n) := 01^n$; we write $\mathbb{X} := \mathbb{Z} \times \mathbb{Z}$ and $X = \{0, 1\}^\mathbb{Z}$ but keep the notation $\phi : \mathbb{X} \to X$ for the substitution map obtained from $\chi$. The general definition of regularity of measures given above corresponds in this case to the definition given in Sec. II, and it is clear that $\mathcal{Q}$ and $Q$ preserve regularity.

Lemma A.6. $\mathcal{Q}$ and $Q$ preserve ergodicity.

Proof. We consider $\mathcal{Q}$ (the proof for $Q$ is similar), and so we must show that if $\nu \in M(\mathbb{X})$, then $\nu(\mathcal{Q})$ is ergodic. We define the probability space $(\Omega, P)$ by $\Omega := \mathbb{X} \times \{0, 1\}^\mathbb{Z}$, $P := \nu \times \kappa$, where $\kappa$ is the Bernoulli measure with parameter $1/2$, and write a typical element of $\Omega$ as $(n, a)$. Then, we can introduce a concrete realization on $\Omega$ of one step of the $\mathcal{Q}$ process, from $n_i$ distributed as $\nu$ to $n_i$ distributed as $\nu(\mathcal{Q})$, as follows. Recall that if $n_0$ has a short stack on either $i$ or $i + 1$, then the movement, or non-movement, of a particle across the bond $(i, i + 1)$, in passing from $n_0$ to $n_1$, is determined by the rule given in Sec. I; we supplement this rule by requiring that if $n_0$ has tall stacks at both $i$ and $i + 1$, then a particle moves from site $i$ to site $i + 1$ if $a(i) = 1$ and from $i + 1$ to $i$ if $a(i) = 0$.

As the product of measures that are, respectively, ergodic and mixing under translations, $P$ is ergodic under translations. It follows that $\nu(\mathcal{Q}) = \nu P$ is the covariant image of an ergodic measure and hence is ergodic.

Theorem A.7. There exists a $τ$-coupling $\mathcal{Q}$ of the Markov transitions kernels $\mathcal{Q}$ and $Q$ for the SSM and F-SSEP.

Proof. As in the definition of $\mathcal{Q}$ and $Q$ in Sec. II, we give the transition rules for a Markov process $(n_0, \eta_0)$ on $X \subset \mathbb{X} \times X$ (see Definition A.7), leaving the specification of $\mathcal{Q}$ as an easy exercise. By Remark A.3, it suffices to consider only the transition from $(n_0, \eta_0)$ to $(n_1, \eta_1)$ for $\eta_0 = \phi(n_0)$. As a preliminary, for $n \in \mathbb{X}$, we define the map $K = K_n$, with $K : \mathbb{Z} \to \mathbb{Z}$, so that $K(i)$ is the starting point of the word $\chi(\zeta(i))$ in the substitution $\phi$.\*
For the dynamics under $\mathcal{Q}$, we allow $n_i$ to evolve to $n_i$ according to the $\mathcal{Q}$ dynamics, and let $n_1$ and $\eta_0$ determine $\eta_1$ as follows. Write $K = K_\eta$. Then, if in passing from $n_0$ to $n_1$, a particle jumps from site $i$ to site $j$, then in passing from $\eta_0$ to $\eta_1$, a particle jumps from site $K(i) = j$ to site $K(i)$, while if a particle jumps from site $i$ to site $i + 1$ in passing from $n_0$ to $n_1$, then one jumps from site $K(i) + 1$ to site $K(i)$ in passing from $\eta_0$ to $\eta_1$. It is straightforward to verify that then $(n_1, \eta_1) \in X$ and with $\eta_1$ distributed according to $Q(\eta_0)$.}

With Lemma A.6 and Theorem A.7, we can apply Corollary A.5 to obtain the correspondence of the F-SSEP and SSM stationary states. The result is summarized in Theorem 2.1.

**APPENDIX B: POSSIBLE ETIS STATES OF THE SSM FOR $\tilde{\rho} > 1$**

In this appendix, we discuss, in the case where Conjecture 5.3 is not satisfied, the passage from stationary states of the SSM on the even sector $\tilde{X}_e^*$ to general ETIS states of the SSM with density $\tilde{\rho} > 1$. By Theorem 5.1, the latter all have support on $\tilde{X}^*$; moreover, as observed in Sec. V, the stationary states on $\tilde{X}^*$ include in addition only $\hat{\rho}$ (2). Let $\mathcal{N}_\rho$ denote the family of stationary states on $\tilde{X}^*_e$ with density $\hat{\rho}$, that is, states $\nu$ for which $\nu$-almost every $n \in \tilde{X}_e^*$ satisfies

\[
\lim_{N \to \infty} \frac{1}{N} \sum_{i=1}^{N} n_i = \lim_{N \to \infty} \frac{1}{N} \sum_{i=1}^{N-1} n_i = \hat{\rho}.
\]

Let $\overline{X}_e^*$ be the extremal elements of $\mathcal{N}_\rho$. We completely analyze the structure of ETIS states on $\tilde{X}^*$, in terms of the states of $\overline{X}_e^*$, in two cases: when for each $\hat{\rho}$, $\overline{X}_e^*$ contains only TI states (Theorem B.1), and when for each $\hat{\rho}$, $\overline{X}_e^*$ is countable (Theorem B.5). The first case is quite simple.

**Theorem B.1.** If all stationary states on $\tilde{X}_e^*$ are translation invariant, then every ETIS state $\rho$ on $\tilde{X}^*$ of density $\tilde{\rho}$ is of the form $\gamma_\lambda (\mu_\sigma \times \lambda)$, with $\lambda$ being an ergodic TI measure on $S$ of density $\kappa$ and $\mu_\sigma \in \overline{X}_e^*$, where $\hat{\rho} = \kappa - \kappa$. Conversely, every state of this form is ETIS.

**Proof.** If $\rho$ is an ETIS state on $\tilde{X}_e^*$ of density $\tilde{\rho}$, then Lemma 5.6 implies that $\rho = \gamma_\lambda \hat{\rho}$ with $\hat{\rho} = (dn \delta\sigma) = \mu_0 (dn) \lambda(d\sigma)$ and $\mu_0 = \tau^*_\rho \mu_\sigma$. However, if all stationary states on $\tilde{X}_e^*$ are TI, then $\mu_0 = \mu_\sigma$ for all $\sigma$ so that the ergodicity of $\lambda$ implies that $\mu_\sigma$ is independent of $\sigma$, $\lambda$-a.s., and extremality of $\rho$ implies that this state, $\mu_\sigma$, must be ETIS on $\tilde{X}_e^*$. The converse is clear.

We now consider the possibility of non-TI stationary states on $\tilde{X}_e^*$. In the next definition, we introduce a class of stationary states on $\tilde{X}_e^* \times S$, which we call basic states, and a further restriction of this class to irreducible basic states.

**Definition B.2.** Let $\lambda$ be an ergodic TI measure on $S$, let $\nu \in \overline{X}_e^*$ have period $n = n(\nu)$ under translation, and let $m$ and $q$ be positive integers such that $n = qm$.

(a) A $(\lambda, m)$-partition of $S$ is an ordered family $A = (A_i)_{i=0}^{m-1}$ of subsets of $S$ such that $S = \bigcup_{i} A_i = S$ and $A_i \cap A_j = \emptyset$ for $0 \leq i, j \leq m - 1$, both up to sets of $\lambda$-measure zero, and such that the family is cyclically permuted by translation: $\tau^k(A_i) = A_{(i+k) \mod m}$. Translations act on such partitions via $(\tau^k A)_i = A_{(i+k) \mod m}$.

(b) Let $\lambda$ be a $(\lambda, m)$-partition of $S$, and let $\nu(\sigma) := q^{-1} \sum_{i=0}^{m-1} \tau^i \nu$. Then, $\hat{\rho}^{(\lambda, m)}(\nu) = (dn \delta\sigma) = \mu_0^{(\lambda, m)}(dn) \lambda(d\sigma)$, where $\mu_0^{(\lambda, m)} = \tau^{\nu(\sigma)}$. Let $\nu(\sigma) \in A_k$, i.e.,

\[
\hat{\rho}^{(\lambda, m)}(\nu) = \sum_{k=0}^{m-1} 1_{A_k}(\nu) \hat{\rho}^{(\lambda, m)}(\nu).
\]

$\rho^{(\lambda, m)}$ and $\mu^{(\lambda, m)}$ will be called basic states.

(c) The basic state $\hat{\rho}^{(\lambda, m)}$ is reduced by the basic state $\hat{\rho}^{(\lambda, m)}$ if $A'$ is a proper refinement of $A$; $\hat{\rho}^{(\lambda, m)}$ is then called reducible, and we say also that $\hat{\rho}^{(\lambda, m)}$ is reducible. If $\hat{\rho}^{(\lambda, m)}$ and $\mu^{(\lambda, m)}$ are reducible, then they are irreducible.

Observe that whether or not $\hat{\rho}^{(\lambda, m)}$ is reducible depends only on $\lambda$, $A$, and $n$, the period of the orbit of $\nu$ under the action of $\tau^\nu$; $\hat{\rho}^{(\lambda, m)}$ is reducible precisely when there is a $(\lambda, m')$-partition $A'$ of $S$ such that $m'$ divides $n$ and $A'$ is a proper refinement of $A$. Equivalently, $\hat{\rho}^{(\lambda, m)}$ is irreducible when the action of $\tau^\nu$ on $A_0$, equipped with the invariant measure $\lambda|_{A_0}$, is ergodic.

We next give some simple consequences of Definition B.2.

**Lemma B.3.** Let $\hat{\rho}^{(\lambda, m)}$ be a basic state. Then, we have the following:

(a) $\hat{\rho}^{(\lambda, m)}$ is stationary.
(b) \( \bar{\mu}^{(k, \nu, \lambda)}(d\nu, d\lambda) = \bar{\mu}^{(k, \nu)}(d\nu, d\lambda) \).
(c) For any \( \sigma \in S \), \( \tau_\sigma \bar{\mu}^{(k, \nu)}(d\nu, d\lambda) = \bar{\mu}^{(k, \nu)}(d\nu, d\lambda) \). In particular, \( \bar{\mu}^{(k, \nu, \lambda)} \) is TI. Moreover, if \( \lambda \) has density \( \kappa \), then \( \bar{\mu}^{(k, \nu, \lambda)} \) has density \( \bar{\mu}_\kappa + \kappa \).
(d) If the basic state \( \bar{\mu}^{(k, \nu, \lambda)} \) reduces \( \bar{\mu}^{(k, \nu)} \), and \( A_0 \subset A_0 \) in \( T \), then \( A_i = \bigcup_{k=0}^{p-1} A^{(k, \nu, \lambda)}(i-j \text{ mod } m) \) for \( i = 0, \ldots, m-1 \), where \( m = |A| \) and \( p = |A'|/|A| \). Moreover, \( \bar{\mu}^{(k, \nu, \lambda)} = \bar{\mu}^{(k, \nu, \lambda)}(d\nu, d\lambda) \).
(e) If \( \bar{\mu}^{(k, \nu, \lambda)} \) is irreducible, then it cannot be written as a convex combination of other \( \bar{\mu}^{(k', \nu', \lambda')} \); more generally, we cannot have
\[
\bar{\mu}^{(k, \nu, \lambda)} = \int \tilde{\mu}^\beta(a(d\beta)),
\]
with \( \beta \) being a probability measure on triples \( \beta = (\lambda', \nu', \lambda) \), which assigns zero probability to \( (\lambda, \nu, \lambda) \).

**Proof.** (a), (b), and (c) are immediate.
(d) The first statement follows from \( A_0 = T^kA_0 \subset T^kA_0 = A_0 \) (mod \( m \)). For the second, it suffices to prove that \( \mu^{(k, \nu)} = p^{-1} \sum_{k=0}^{p-1} \tilde{\mu}(d\nu, d\lambda) \)

\[
= \int \tilde{\mu}(d\nu, d\lambda) \]

Thus, we are reduced to the case where \( \tilde{\mu}^{(k, \nu, \lambda)} \) is TI, as follows.

**Lemma B.4.** If \( \nu, \lambda \) is countable for each \( \nu \leq 1 \), then each ET \( \nu \) state on \( \mathbb{X}^* \) is an irreducible basic state.

**Proof.** We write \( \mathbb{X}_i = \{ \nu_i \}_{i \in \mathbb{Z}} \), with \( \nu \) either \( \mathbb{Z} \) or a finite set \( \{ 1, 2, \ldots, J \} \), and allow the translation operator \( \tau \) to act on \( \mathbb{J} \) via \( \nu_j = \tau_j \nu_j \).

Let \( \mathbb{J} \) denote the set of orbits in \( \mathbb{Z} \) under translation.

Now let \( \mu \) be an ET \( \nu \) state on \( \mathbb{X} \) of density \( \bar{\mu} \). Then, from Lemma 5.6, we know that \( \mu = \gamma \bar{\mu} \) with \( \bar{\mu}(d\nu, d\lambda) = \mu(d\nu, d\lambda) \). \( \lambda \) being ergodic, \( \mu_\sigma \) being stationary, and \( \mu = \tau \mu \).

For each \( \sigma \in S \), we have \( \mu_\sigma \sum_{k \in \mathbb{Z}} a_{\sigma, k} \nu_j \) with coefficients \( a_{\sigma, k} \) that, from translation invariance, satisfy \( a_{\sigma, k} = a_{\sigma, k} \). Now note that if \( c \in \mathbb{J} \), then \( \rho^{(c)}(d\nu, d\lambda) = \sum_{k \in \mathbb{Z}} a_{\sigma, k} \nu_j \) is TI and, hence, constant \( \lambda \)-a.s.; from now on, we write this as \( \rho^{(c)} \). Define \( \rho^{(c)} \) by \( \rho^{(c)}(d\nu, d\lambda) = \rho^{(c)}(d\nu, d\lambda) \lambda(d\nu, d\lambda) \), so that \( \tilde{\mu}^{(c)} = \sum_{c \in \mathbb{J}} \rho^{(c)}(d\nu, d\lambda) \). Since the \( \rho^{(c)} \) are TI, the extremality of \( \tilde{\mu} \) implies that \( \tilde{\mu} = \rho^{(c)} \) for some \( c_0 \in \mathbb{J} \).

We claim that \( c_0 \) must be a finite set. Otherwise, we may fix \( \delta _j \in c_0 \) and define \( f : S \to \mathbb{Z} \) by
\[
f(\sigma) := \min \{ i \in \mathbb{Z} \mid a_{\sigma, i} = \max_{l \in \mathbb{Z}} a_{\sigma, l} \},
\]

\( f \) satisfies \( f(\sigma) = f(\sigma) + 1 \) so that by the translation invariance of \( \lambda \), the sets \( f^{-1}(\{ k \}) \) are equal \( \lambda \)-measure, a contradiction.

Thus, we are reduced to the case where \( c_0 \) contains \( n \) elements, that is, if \( \delta_j \in c_0 \), then \( n \) is the minimal period for \( \nu_j \), and
\[
\mu = \sum_{i=0}^{n-1} a_{\sigma, i} \nu_j \tau_j \nu_j.
\]

We regard \( a_{\sigma, i} \) as an element of \( \mathbb{R}^n \) and let translations act on \( \mathbb{R}^n \) via \( \tau(b_0, \ldots, b_{n-1}) = (b_{n-1}, b_0, \ldots, b_{n-2}) \) so that \( a_{\sigma, i} = \tau a_{\sigma, i} \). The orbit of \( a_{\sigma, i} \) under this action is independent of translations in \( \sigma \) and, hence, constant, \( \lambda \)-a.s.; let \( \theta \) denote this orbit.
\[ |\theta| \] is a positive integer \( m \) satisfying \( n = qm \) for some integer \( q \). Let \( \theta = \{ v_0, \ldots, v_{m-1} \} \), with \( v_{t} = v_{(t+1) \mod m} \), let \( A_k := \{ \sigma | a_{\sigma} = v_k \} \), and note that if \( w \in \mathbb{R}^m \) is defined by \( w_{i} = qv_{(i\mod m)} \), then \( w \) is independent of \( \sigma \) and \( \sum_{i=0}^{m-1} w_{i} = 1 \). Then, from (B8), we find, using (B2), that \( \mu_{0} = \sum_{i=0}^{m-1} w_{i} \mu_{\theta} (v_{i}, \tau^{-A}) \). Thus, \[ \hat{\mu} = \sum_{i=0}^{m-1} w_{i} \mu_{\theta} (v_{i}, \tau^{-A}) \tag{B9} \]

However, since \( \hat{\mu} \) is extremal, precisely one of the \( w_{i} \) can be nonzero so that \( \hat{\mu} \) is basic. It then follows from Lemma B.3 (d) that \( \hat{\mu} \), and hence \( \mu \), is irreducible basic.

Now, we can give the second main result of this appendix.

**Theorem B.5.** If \( \mathcal{N}_{\hat{p}_{c}} \) is countable for each \( \hat{p}_{c} \geq 1 \), then the ETIS states on \( \hat{X}^{*} \) are precisely the basic irreducible states.

**Proof.** Lemma B.4 tells us that every ETIS state is an irreducible basic state. It follows from this that the decomposition of any irreducible basic state into ETIS components must be of the form (B3) and hence, by Lemma B.3 (e), that such a state must be ETIS.

**REFERENCES**